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**A DATA MINING TRAJECTORY CLUSTERING
METHODOLOGY FOR MODELING
INDOOR DESIGN SPACE UTILIZATION**

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PRESENTATION OVERVIEW

- Research Motivation
- Methodology
 - Trajectory Partitioning
 - Line Segment Clustering
- Case Study
- Conclusion and Path Forward





RESEARCH MOTIVATION



How to capture and quantify dynamics in an indoor space ?





Existing Techniques for Assessing Indoor Space Utilization

❖ Qualitative Methodologies

-Observations, interview-based and questionnaire-based surveys [1-3].

Subjective bias.

❖ Quantitative Methodologies

-Layout Optimization techniques [4-5]. E.g. Material flow optimization [5].

-Statistical Analysis [6-10]. E.g. Pyramid based methodology [6].

Pre-determined trajectory paths.





Research Objective

A data mining driven methodology is proposed to quantify and model common trajectory movement patterns in order to predict team dynamics and enhance indoor space design.

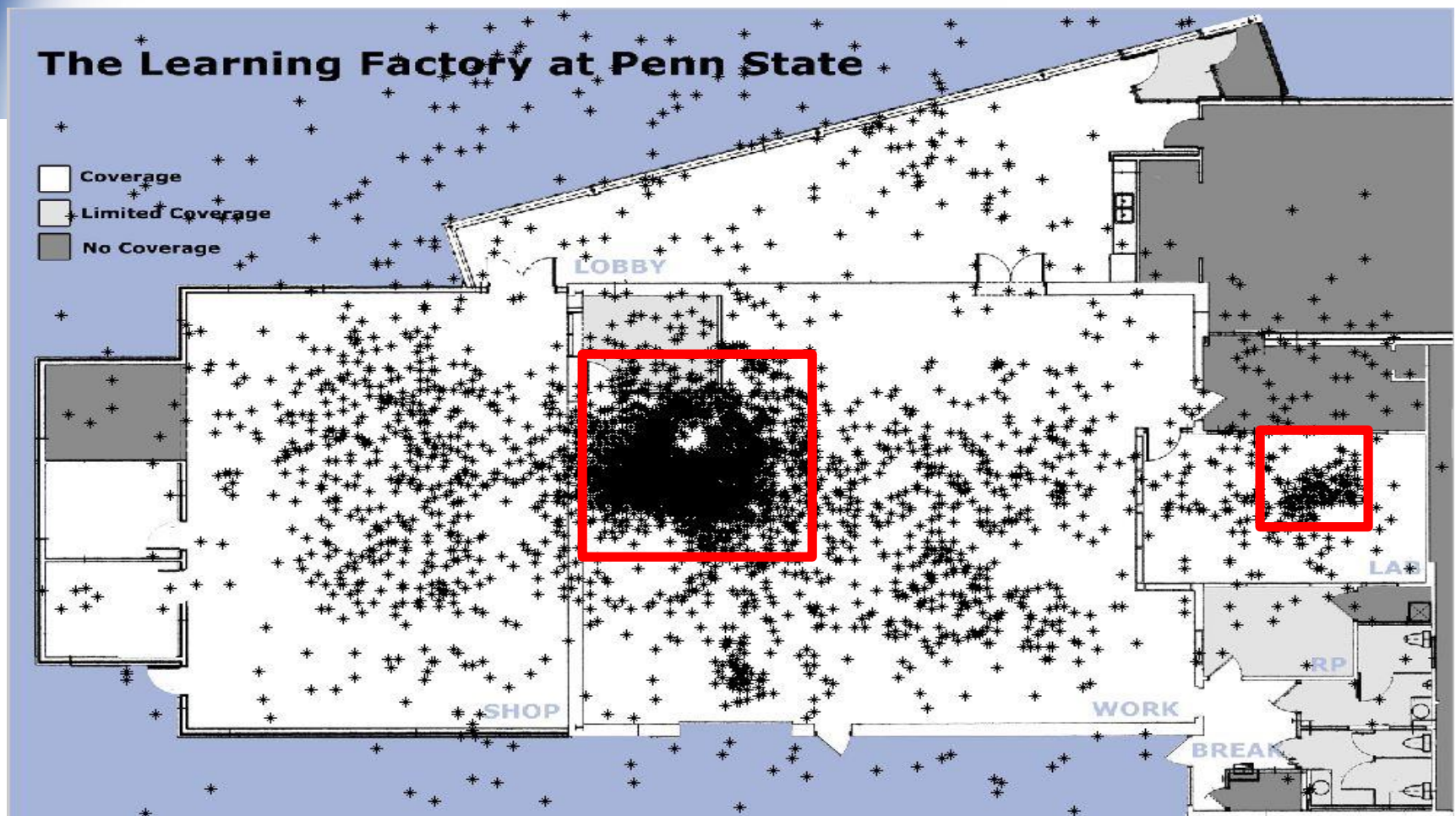




RESEARCH METHODOLOGY



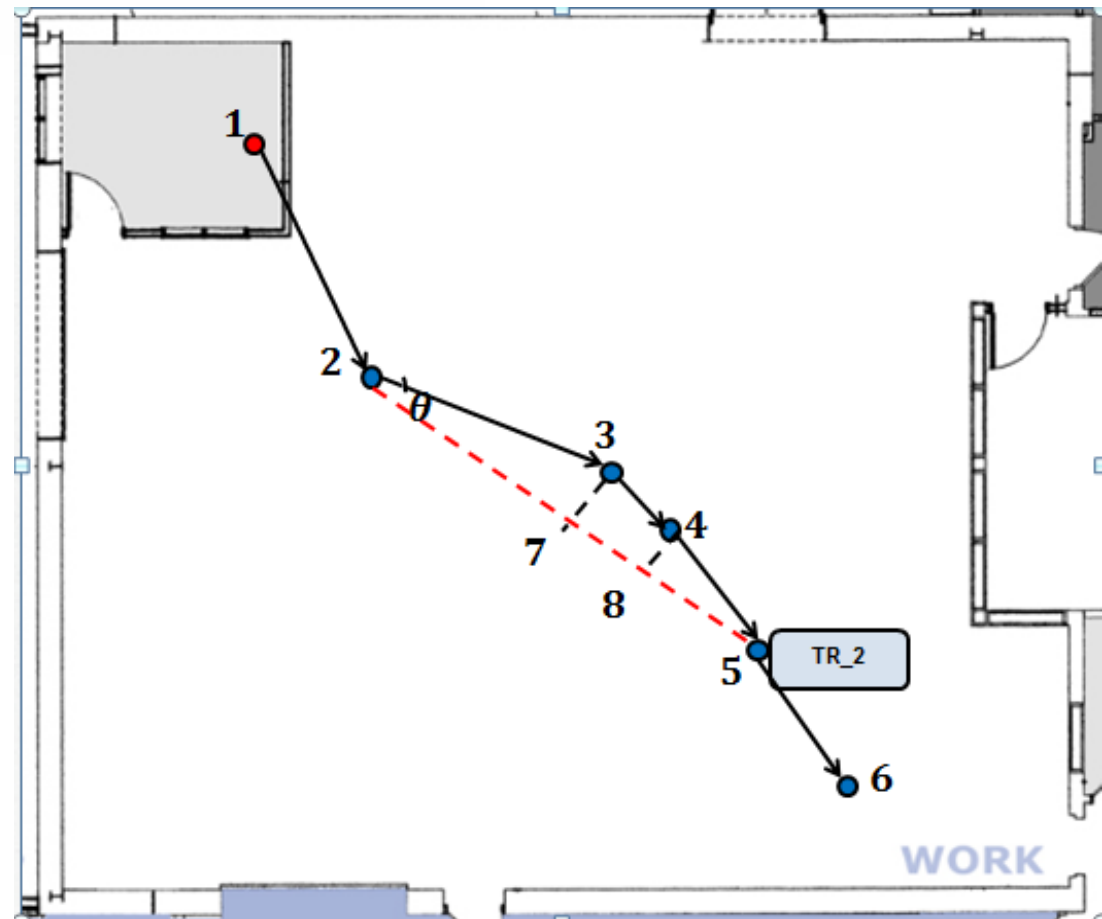
What do we get from this trajectory mapping?



Individual Trajectory Partitioning Example

Original trajectory data set:
 $T_2 = \{t_1, t_2, \dots, t_6\}$.

Characteristic point data set:
 $P_2 = \{p_1, p_2, p_5, p_6\}$,
 which is an approximation
 of the original trajectory.



Q: How to select characteristic point ?

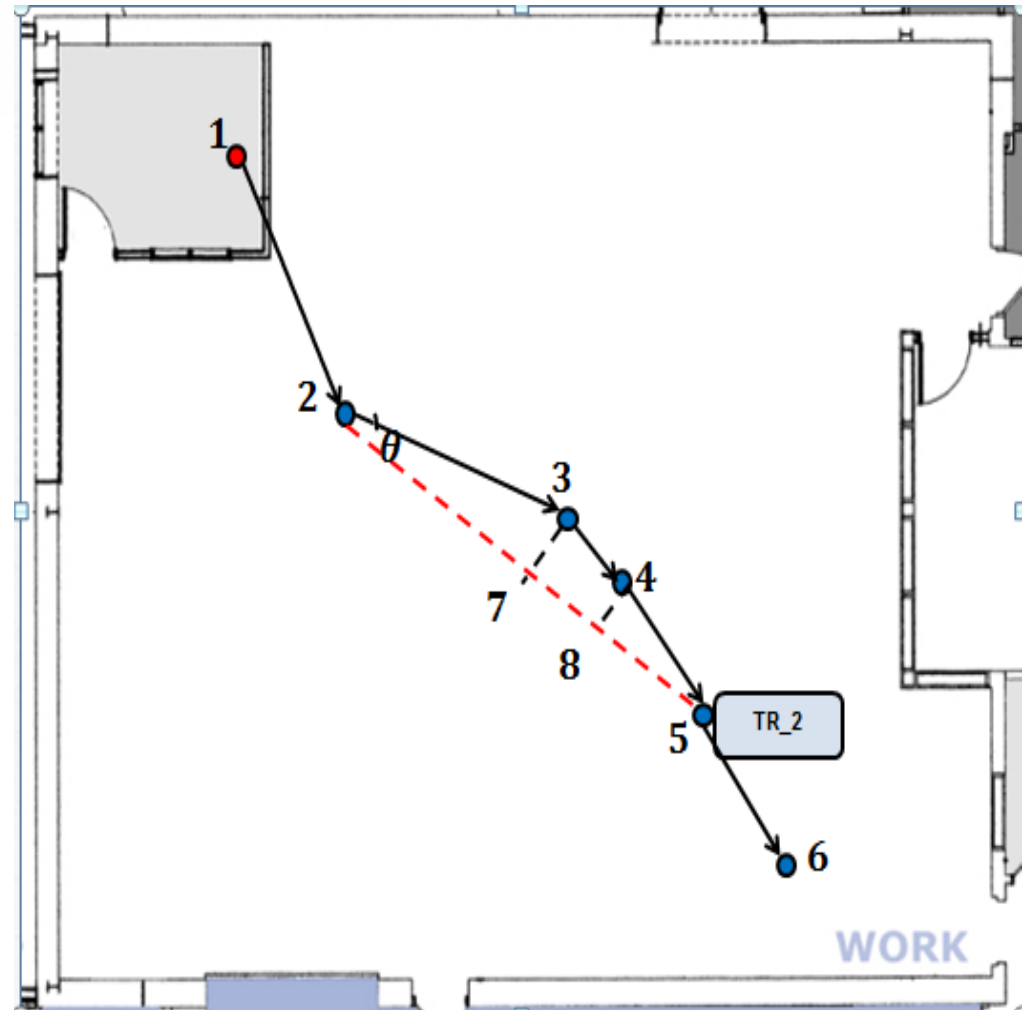
The **Minimum Description Length (MDL)** is applied to extract characteristic points [11].

If $MDL_{par}(t_k) > MDL_{nonpar}(t_k)$, then t_{k-1} would be a characteristic point.

e.g.

$$MDL_{par}(t_5) < MDL_{nonpar}(t_5)$$

$$MDL_{par}(t_6) > MDL_{nonpar}(t_6)$$





Trajectory Clustering

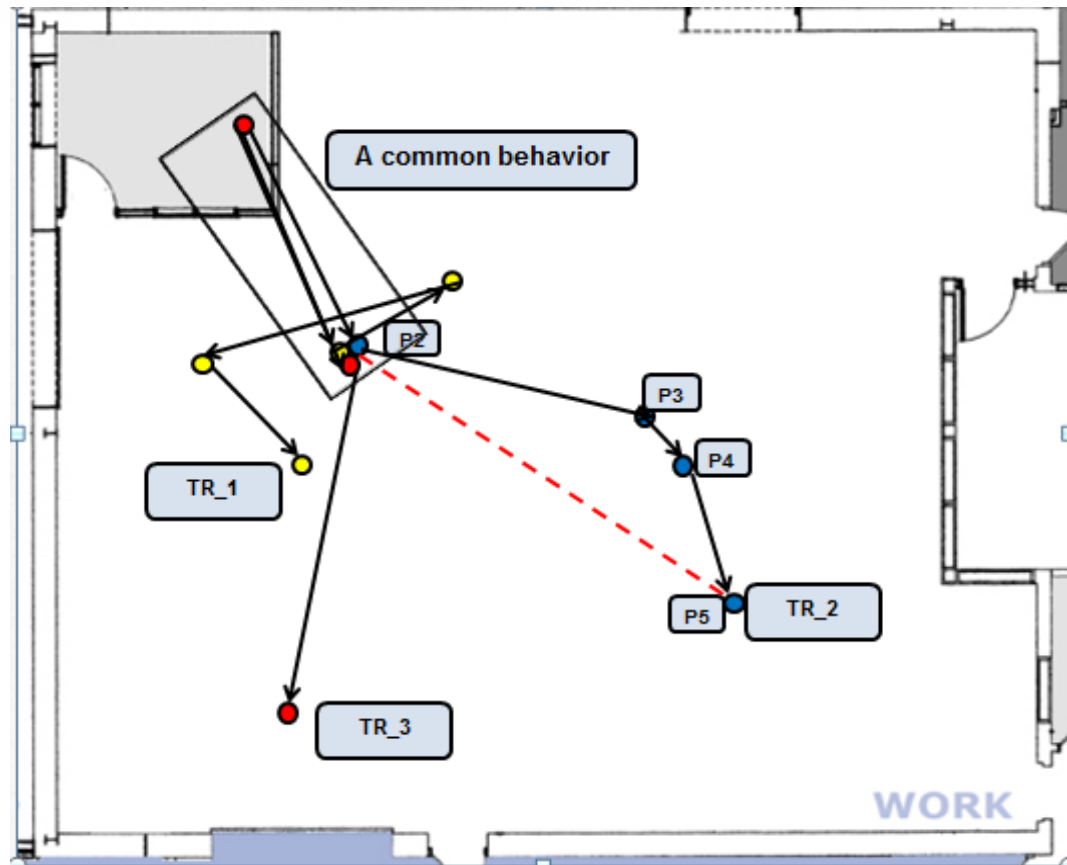
Given the extracted characteristic points $P = \{p_1, p_2, \dots, p_m\}$ from each trajectory, the clustering algorithm will group different individual movement patterns into different clusters $C = \{c_1, c_2, \dots, c_n\}$ where common movement patterns are shared.



Trajectory Clustering Example

Three trajectories **TR_1**, **TR_2** and **TR_3** are described by characteristic points.

The line segments in the rectangular are close enough to each other, and they are considered as a cluster.

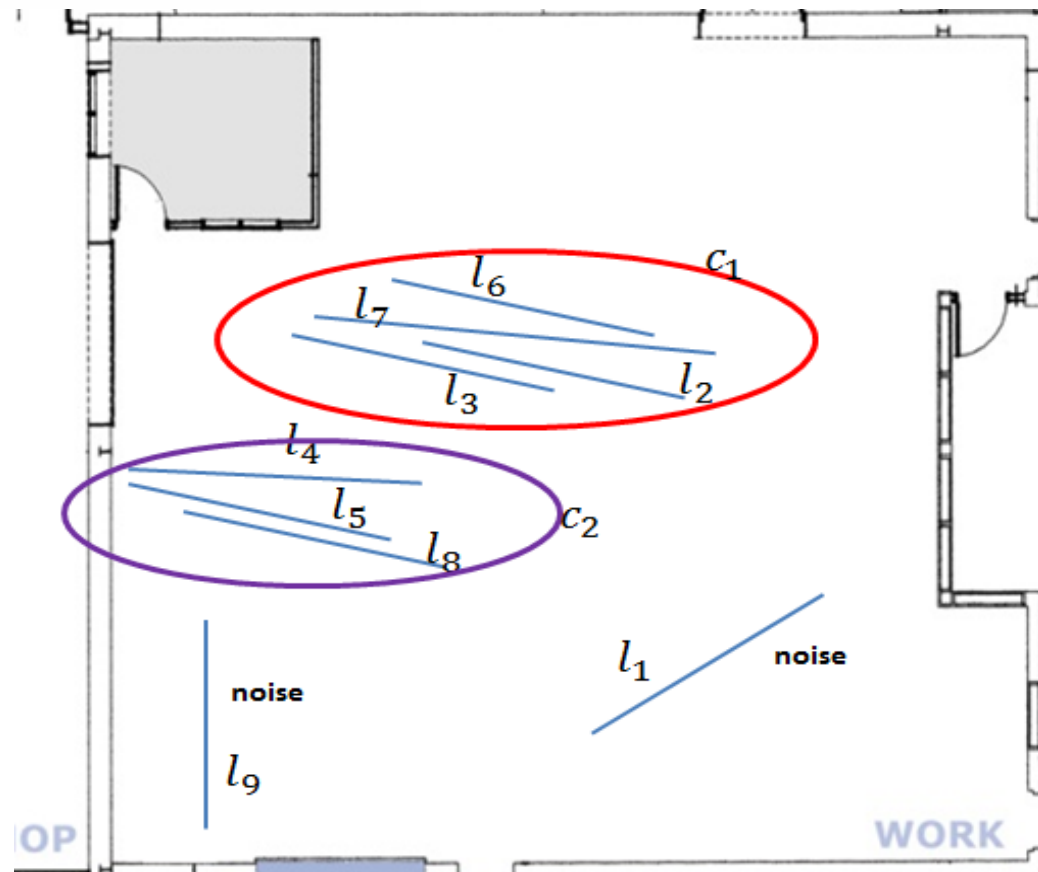


Q: How to generate cluster?

The number of neighborhood of every line segment $N_{\epsilon}(l_i)$.

If $N_{\epsilon}(l_i) \geq \text{MinLns}$, then a density-based set is generated.

If the cardinality ($N_{\epsilon}(l_i) > 1$), then a cluster is generated.



Trajectory Clustering Example

$L = \{l_1, l_2, \dots, l_9\}$. Noise set $Q = \emptyset$.

Step 1:

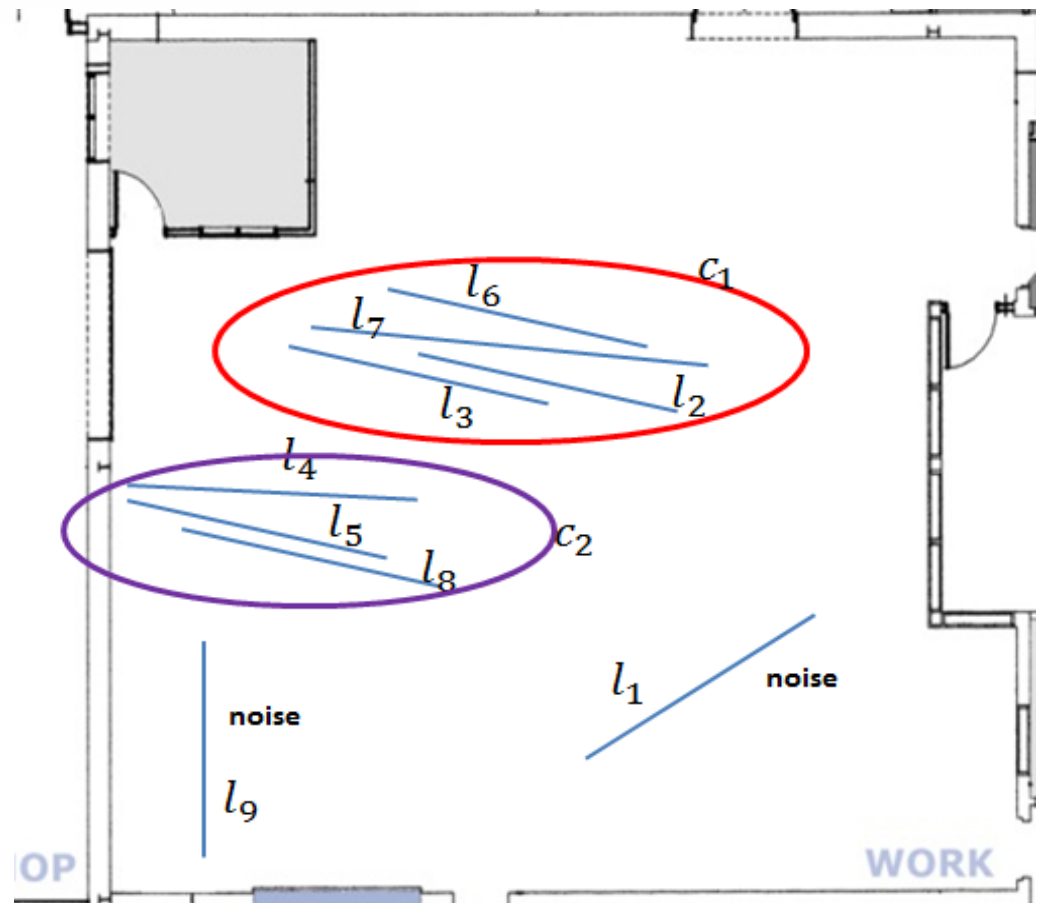
No cluster, $L = \{l_2, \dots, l_9\}$, $Q = \{l_1\}$.

Step 2:

$c_1 = \{l_2, l_3, l_6, l_7\}$, $L = \{l_4, l_5, l_8, l_9\}$, $Q = \{l_1\}$.

Step 3:

$c_1 = \{l_2, l_3, l_6, l_7\}$, $c_2 = \{l_4, l_5, l_8\}$, $L = \emptyset$
 $Q = \{l_1, l_9\}$





Learning Factory Indoor Space Utilization Case Study





Learning Factory at Penn State

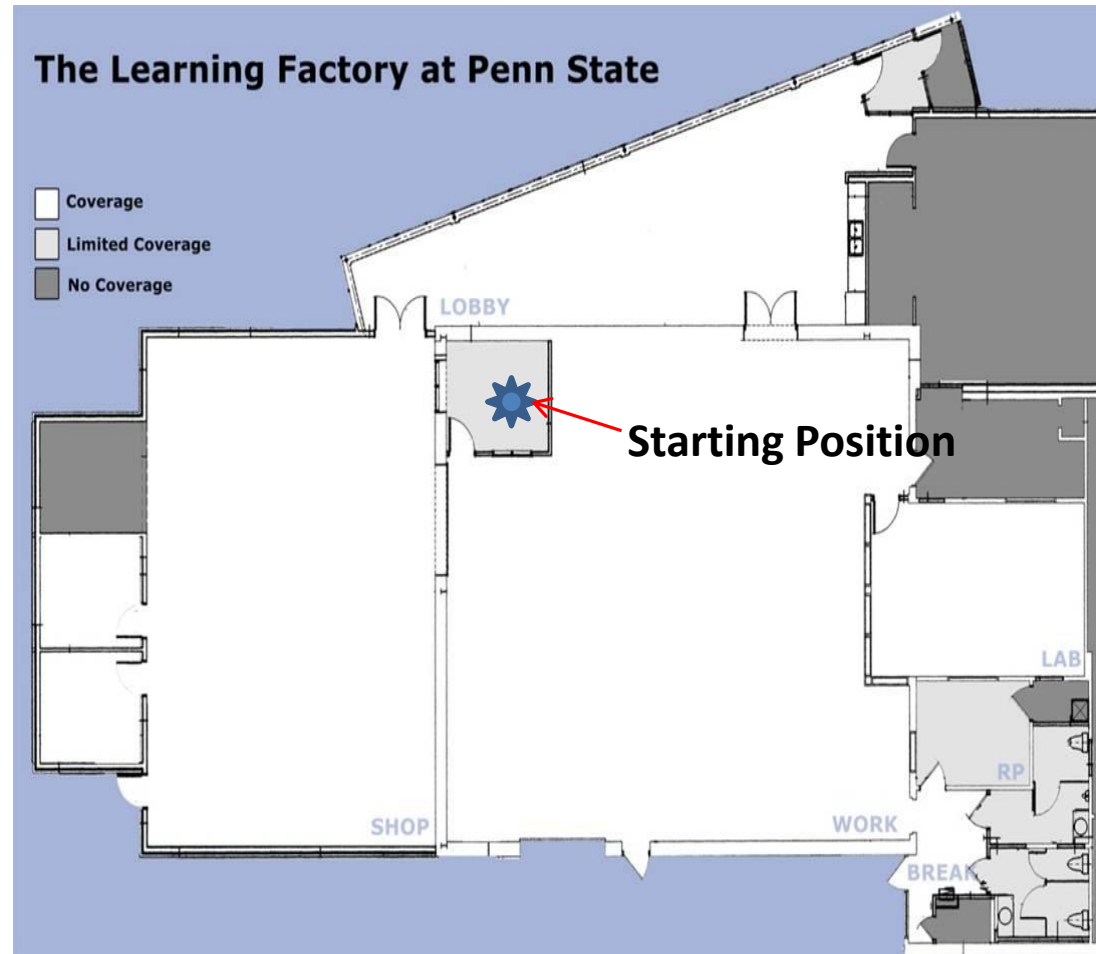
- ❖ The Learning Factory (LF) at Penn State provides student-oriented design/prototyping space for the College of Engineering at Penn State, particularly capstone design projects [12-13].
- ❖ An expansion of the LF facility in 2007 doubled its square footage; however, the program has seen explosive growth as more departments have become engaged [14].



Learning Factory Layout

Twelve tags were provided for teaching assistants (TAs).

A TA would wear one of the tags and then guide student experiments normally until the work is done and put the tag back to the container.





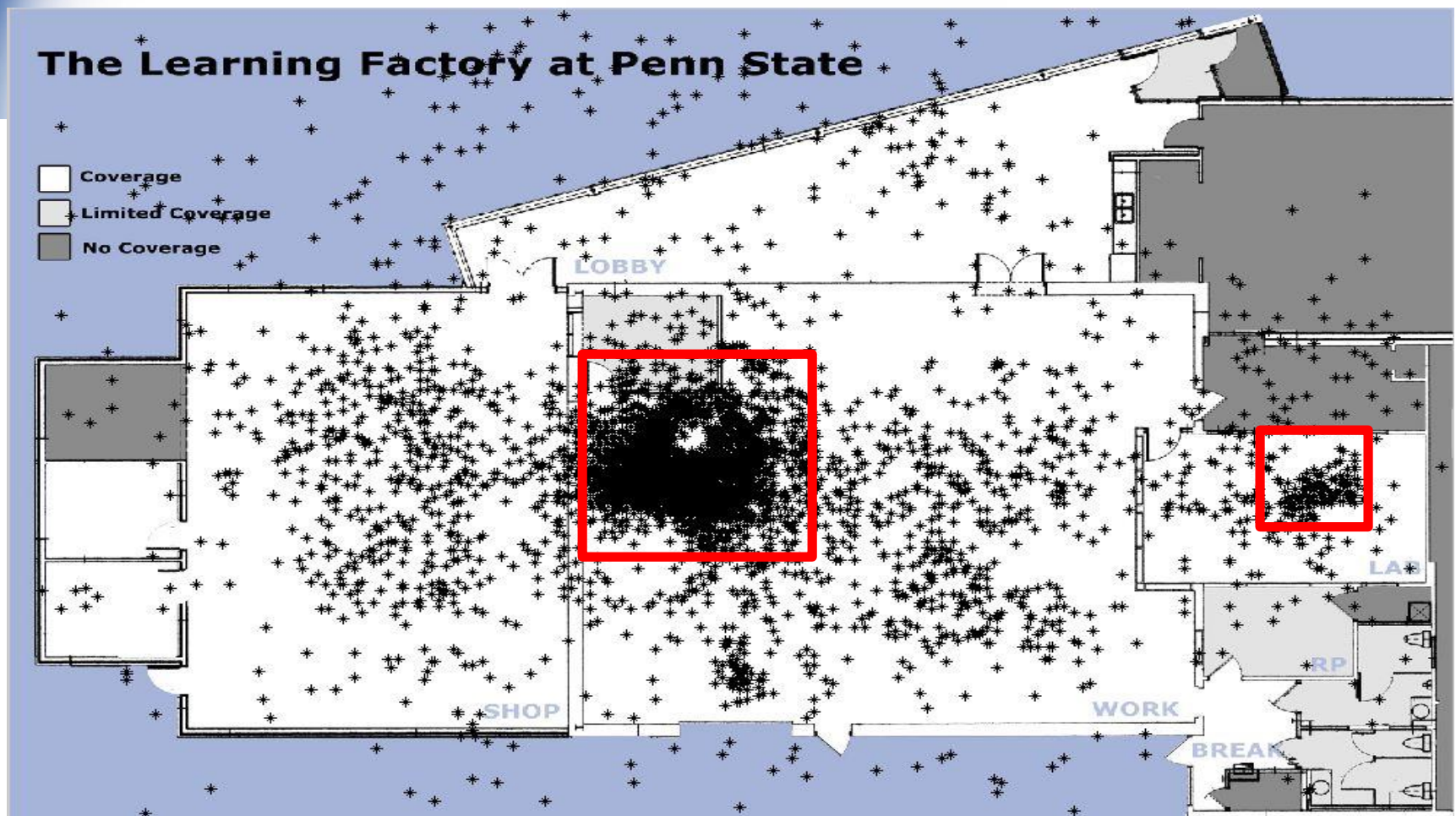
Clustering Result

TABLE 2. Statistical clustering result

Cluster No.	Total number of line segments	Cluster cardinality
C1	58	20
C2	41	18
C3	8	3
C4	42	15
C5	15	8
C6	59	14
C7	48	14
C8	224	46
C9	322	44



What do we get from this trajectory mapping?

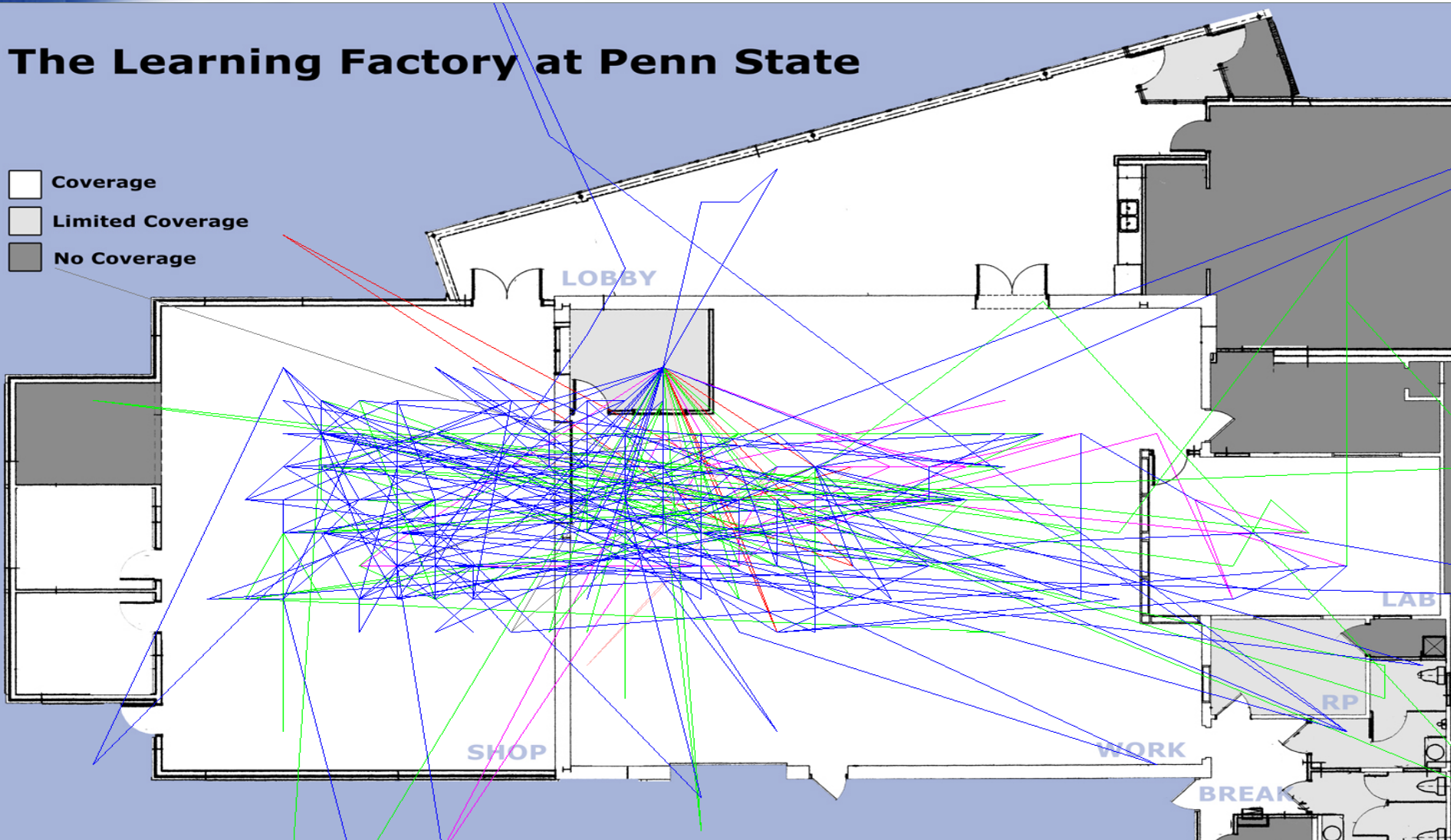




Visualization

The Learning Factory at Penn State

- Coverage
- Limited Coverage
- No Coverage





Results:

1. Nine types of common movement patterns are generated.
2. Cluster 8 and Cluster 9 can explain the most significant movement patterns as large number of individuals are included. At the same time, we can see the “back-and-forth” pattern represented.
3. Two middle spaces are most utilized regions. In addition, they are always utilized simultaneously in the Learning Factory.





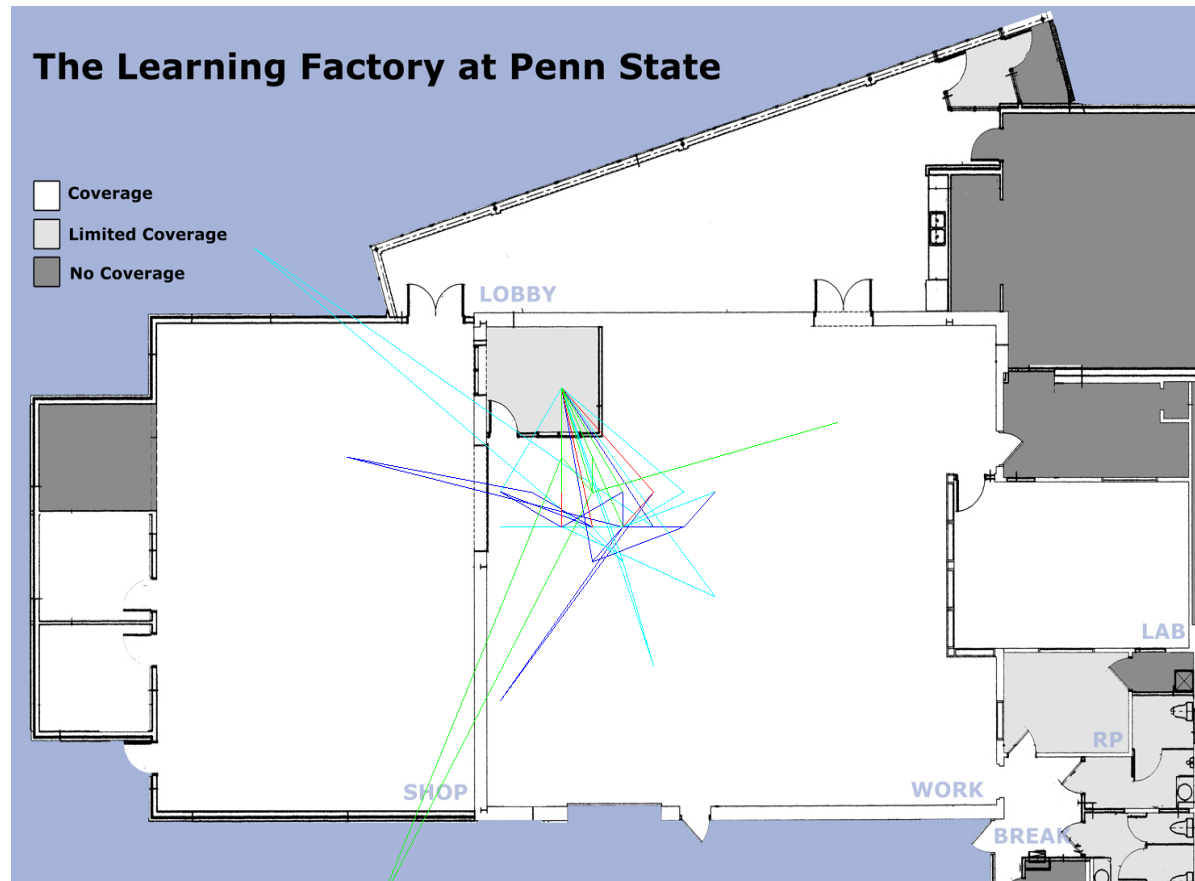
Movement Pattern Evolution Detection

The objective: detect any change of indoor space utilization patterns in the Learning Factory.



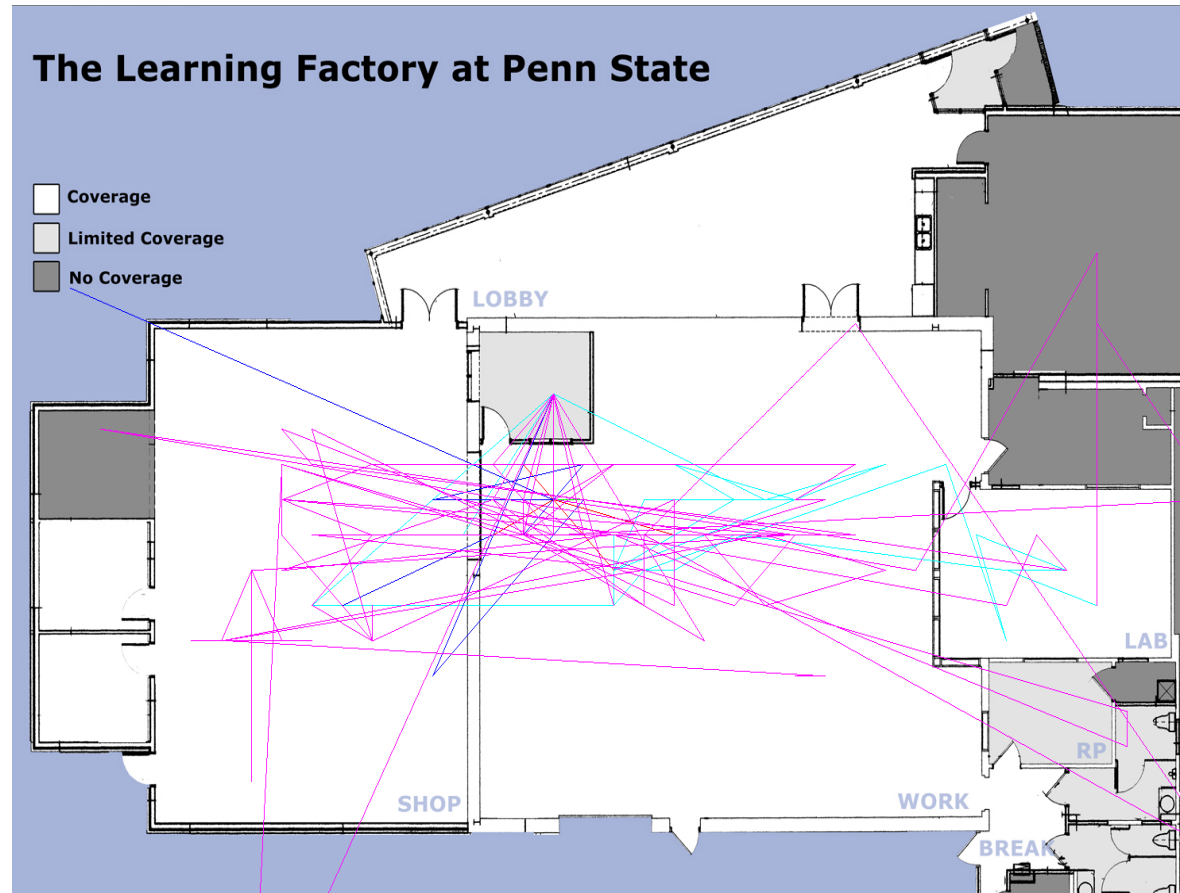
Visualization of Period I (01/20/2012 to 02/21/2012)

- ❖ Four clusters.
- ❖ Part of the middle spaces are utilized.



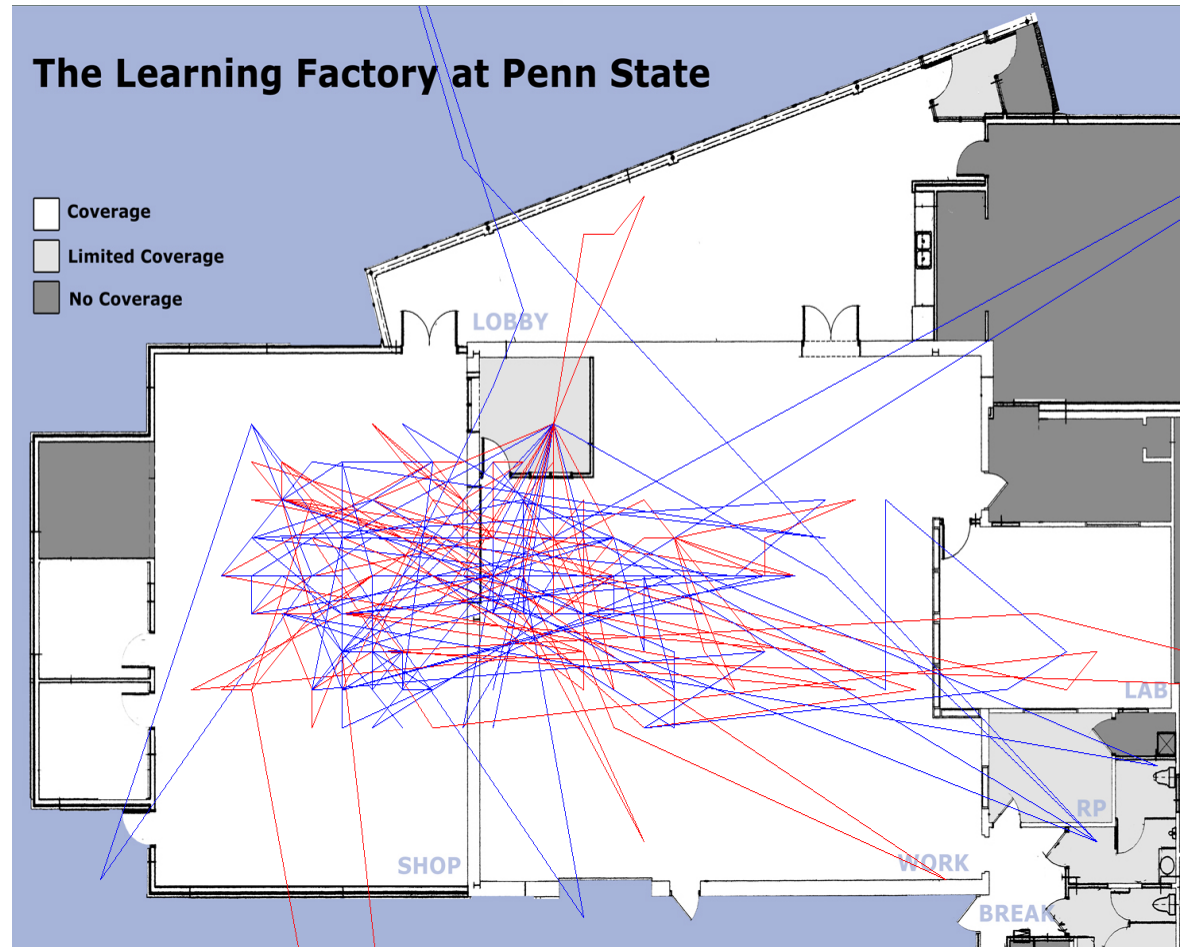
Visualization of Period II (02/22/2012 to 03/22/2012)

- ❖ Four clusters.
- ❖ More spaces are utilized including Lab Space and Toilet.



Visualization of Period III (03/23/2012 to 04/23/2012)

❖ Only two clusters which means the trajectory patterns are tend to be more similar comparing to the first two periods.





Results:

- Utilized spaces are increasing from the Period I to the Period 3.
- The similarities among multiple clusters are increasing from the Period I to the Period 3 since the number of clusters are decreasing from Period I to Period III.





Conclusion:

In this paper, we propose a data mining driven methodology which is able to model and predict common trajectory movement patterns in order to understand team dynamics and navigate indoor space design.





Future Work





Future Work

1. Include indoor facility layout optimization to enhance team dynamics and overall project quality ;
2. Explore other potential indoor space design applications such as emergency room in hospital, etc.



Acknowledgement

Contributors:

- Yixiang Han, Conrad S. Tucker, Yixiang Han, Timothy W. Simpson, Erik Davidson.

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Thank you

Q & A

